Capturing the Dynamics of Compound Flooding in E3SM

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Scientific Discovery through Advanced Computing

Scientific **D**iscovery through **A**dvanced **C**omputing (SciDAC)



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- Started in 2001 (1st)
- Re-competed in 2006 (2nd), 2011 (3rd), 2017 (4th), and 2022 (5th)
- Current SciDAC Institutes include:
 - 1. FASTMath
 - 2. RAPIDS
- Current SciDAC BER partnerships include 7 projects

Compound Flooding (CF)

Compound events are described as (IPCC2012)

- 1. simultaneous or successively occurring (climate-related) events such as simultaneous coastal and fluvial floods,
- 2. events combined with background conditions that augment their impacts such as rainfall on already saturated soils, or
- 3. a combination of (several) average values of climatic variables that result in an extreme event



CF and Its Impacts Pose a Significant Threat to Human and Natural Systems



https://www.usgs.gov/observatories/yvo/news/how-might-devastating-june-2022-floods-and-around-yellowstone-national-park

CF and Its Impacts Pose a Significant Threat to Human and Natural Systems



Several **S**cientific and **C**omputational **B**ottlenecks Exists in E3SM for Studying CF and Its Impacts

- $\blacktriangleright\,$ SB1: MOSART's assumption about subgrid structure limits the finest mesh resolution to be $\approx\,5{\rm km}$
- SB2: MOSART's existing physics has few limitations in accurately capturing CF events
 - Backwater propagation occurs only along river network
 - Instantaneous exchange of water between river channel and floodplain
 - Lack of density-dependent flow
- CB1: Single discretization implementation does not allow for the evaluation of numerical algorithms for solution accuracy and algorithmic scalability
- CB2: No support for heterogeneous computing architectures

Project Objectives (POs)



- PO1: Develop a rigorously verified and validated river dynamical core (RDycore) for E3SM to mechanistically model pluvial, fluvial, and coastal compound flooding and their impacts on sediment dynamics and riverine saltwater intrusion.
- PO2: Develop computationally efficient and scalable RDycore and assess its performance on heterogeneous computing architectures.
- PO3: Improve the predictive understanding of CF, SD, and rSWI due to the simultaneous but uncertain occurrence of multiple drivers of floods in a changing climate.

Research Foci



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- 5. Added RDycore within E3SM and performed short simulations on Perlmutter, Summit, Crusher, and Frontier with RDycore using GPUs.



Team member: Gautam Bisht

RDycore: Initial Development and Verification

- ▶ Implemented first-order accurate space (FV) and time (explicit) discretization methods
- Works on both triangle and quadrilateral mesh
- Performed initial code verification for two previously published problems





Development of Benchmarks: Houston Harvey Flooding





UMesh3 with 57,098 cells



- Selected Overland Flow Model (OFM)
- Selected the Houston Harvey flooding event, August 2017
- Spatially-homogenous, but temporally varying precipitation forcing is applied
- A time-varying tidal stream outflow BC is used
- When coarsening the mesh, the simulation efficiency increases, but accuracy decreases



Development of Benchmarks: Sediment Dynamics

- Selected TELEMAC-MASCARET as the benchmark model
- Selected the Janauaca catchment in the Amazon as the study site
- Completed a 10-yr flow simulation with 8 inflow BCs and 3 open flow BCs
- Performed an initial 1-yr sediment dynamics simulation



Unstructured meshes: global-to-(sub)watershed scales...

Push E3SM unstructured meshing workflow (JIGSAW library) to new 'ultra' high-resolution floodplain resolving levels.



Support additional boundary 'labelling' of geometry as well as XDMF/EXODUS file I/O, for PETSc interoperability.

PETSc and libCEED solver GPU/device portability

- Non-linear SWE: $\mathbf{X}_t = F(\mathbf{X})$
- PETSc provides multiple time integration methods
- Portability provided with two options on most architectures:
 - Vendor specific back-ends: CUDA, HIP
 - Kokkos back-end: eg, CUDA, HIP, SYCL, and OpenMP

Programming Model	Supporting Package	GPUs (devices)
CUDA	cuBLAS, cuSPARSE, Thrust	NVIDIA
HIP	hipBLAS, hipSparse, hipThrust	AMD
Kokkos	Kokkos, Kokkos-Kernels	NVIDA, AMD, Intel

- libCEED has been extended for FV method to compute the F(X) on the device
- PETSc's DMPlex has been extended to support libCEED's FV method

E3SM–RDycore Integration



- A test implementation of E3SM–RDycore has been completed.
- PETSc and RDycore are installed before building an E3SM case.
- RDycore initializes a simulation, runs to completion, and shuts off.
- RDycore tested on GPUs: (a) NVIDIA (Perlmutter and Summit) and (b) AMD (Crusher and Frontier).
- However, presently there is no exchange of information between ELM and RDycore.
- Exploited PETSc's runtime configurability to solve SWE on CPU or GPU via:
 - CPU : e3sm.exe
 - GPU via Kokkos: e3sm.exe -dm_vec_type kokkos
 - GPU via CUDA : e3sm.exe -dm_vec_type cuda
 - GPU via HIP : e3sm.exe -dm_vec_type hip



Thank you